

Chapter 28

Sources of Magnetism



Copyright © 2005 Pearson Prentice Hall, Inc.

Units of Chapter 28

- 28.1 Magnetic Field Due to a Long Straight Wire
- 28.2 Force between Two Parallel Wires: 1 - 8
- †28.3 Operational Definitions of the Ampere and the Coulomb
- 28.4 Ampère's Law
- †28.5 Magnetic Field of a Solenoid and Toroid: 9 - 12
- †28.6 Biot-Savart Law: 13 & 14

Units of Chapter 28

- †28.7 Magnetic Materials - Ferromagnetism: 15
- 28.8 Electromagnets and Solenoids
- †28.9 Magnetic Fields in Magnetic Materials; Hysteresis
- †28.10 Paramagnetism and Diamagnetism

28.1 Magnetic Field Due to a Long Straight Wire

The field is inversely proportional to the distance from the wire:

$$B = \frac{\mu_0 I}{2\pi r}$$

The constant μ_0 is called the permeability of free space, and has the value:

$$\mu_0 = 4\pi \times 10^{-7} \text{ T}\cdot\text{m/A}$$

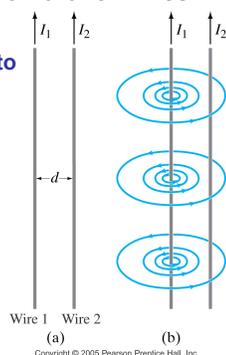
28.2 Force between Two Parallel Wires

The magnetic field produced at the position of wire 2 due to the current in wire 1 is:

$$B_1 = \frac{\mu_0 I_1}{2\pi d}$$

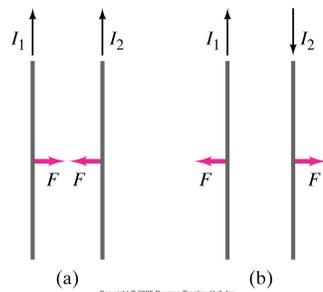
The force this field exerts on a length l_2 of wire 2 is:

$$F_2 = \frac{\mu_0 I_1 I_2}{2\pi d} l_2$$



28.2 Force between Two Parallel Wires

Parallel currents attract; antiparallel currents repel.



28.4 Operational Definitions of the Ampere and the Coulomb

Definition of the Ampere
 Definition of the Coulomb
 Additional Notes online

$1 \text{ A} = 1 \frac{\text{C}}{\text{s}}$

28.4 Operational Definitions of the Ampere and the Coulomb

Definition of the Ampere
 Definition of the Coulomb
 Additional Notes online

28.4 Ampère's Law

Ampère's law relates the magnetic field around a closed loop to the total current flowing through the loop.

$$\sum B_{\parallel} \Delta l = \mu_0 I_{\text{encl}}$$

Closed path made up of segments of length Δl
 Area enclosed by the path

Copyright © 2005 Pearson Prentice Hall, Inc.

28.4 Ampère's Law

Ampère's law relates the magnetic field around a closed loop to the total current flowing through the loop.

$\sum B_{\parallel} \Delta l = \mu_0 I_{\text{encl}}$

$\oint \vec{B} \cdot d\vec{l} = \mu_0 I_{\text{encl}}$

$B(2\pi r) = \mu_0 I_{\text{encl}}$

Closed path made up of segments of length Δl

Area enclosed by the path

Copyright © 2005 Pearson Prentice Hall, Inc.

$$F = I l B \quad B = \frac{\mu_0 I}{2\pi r}$$

$$\frac{F}{l} = I B = \frac{\mu_0 I_1}{2\pi r} I_2$$

a) $r > R$

$$\oint \vec{B} \cdot d\vec{l} = \mu_0 I_{\text{encl}}$$

$$B(2\pi r) = \mu_0 I_{\text{encl}}$$

$$B = \frac{\mu_0 I_{\text{encl}}}{2\pi r}$$

b) $r < R$ $I_{enc} = I_{tot} \frac{\pi r^2}{\pi R^2}$

$$\oint \vec{B} \cdot d\vec{l} = \mu_0 I_{enc}$$

$$B(2\pi r) = \mu_0 I_{tot} \frac{r^2}{R^2}$$

$$B = \frac{\mu_0 I_{tot} r}{2\pi R^2}$$

c) $r = R$

$$B = \frac{\mu_0 I_{tot} r}{2\pi R^2} = \frac{\mu_0 I_{tot} r}{2\pi r^2}$$

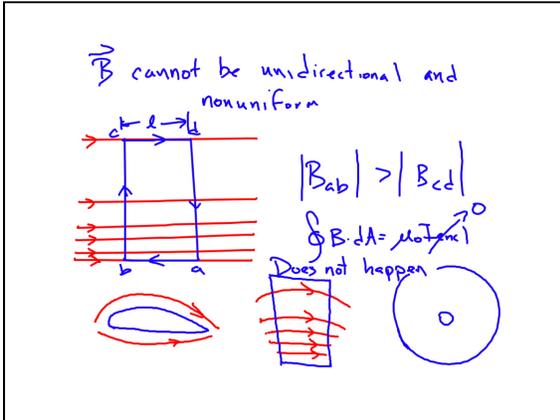
$$B = \frac{\mu_0 I}{2\pi r}$$

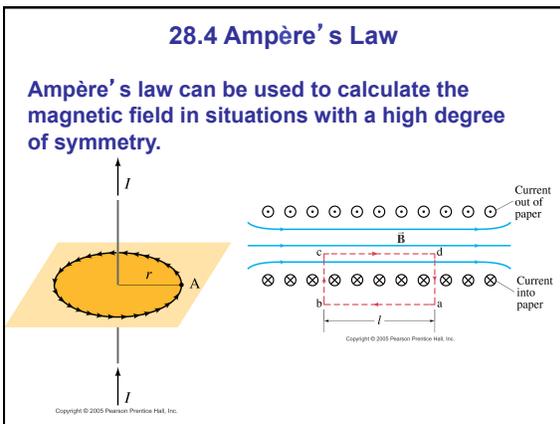
\vec{B} cannot be unidirectional and nonuniform

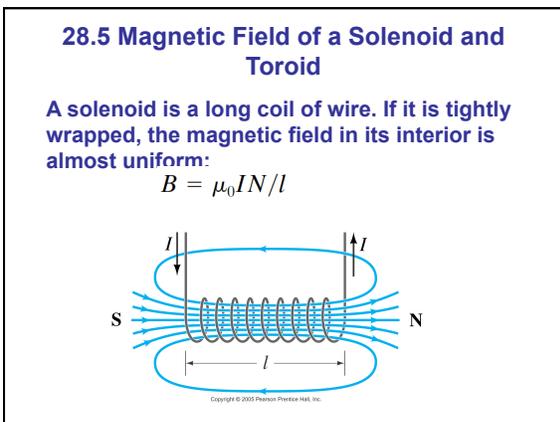
$|B_{ab}| > |B_{cd}|$

$$\oint \vec{B} \cdot d\vec{A} = \mu_0 I_{enc}$$

Does not happen







Solenoids

$$\oint \vec{B} \cdot d\vec{l} = \int_a^b \vec{B} \cdot d\vec{l} + \int_b^c \vec{B} \cdot d\vec{l} + \int_c^d \vec{B} \cdot d\vec{l} + \int_d^a \vec{B} \cdot d\vec{l}$$

$B \rightarrow 0$ $\cos 90^\circ = 0$ $\cos 90^\circ = 0$

$$\oint \vec{B} \cdot d\vec{l} = \int_c^d B \cdot dl = Bl = \mu_0 I_{enc}$$

$$Bl = \mu_0 NI \Rightarrow B = \mu_0 \frac{N}{l} I = \mu_0 n I$$

IMPORTANT NOTE: n is equal to the number of loops per unit length (aka. Loop Density). It is NOT the number of wires!

28.5 Magnetic Field of a Solenoid and a Toroid

Ampère's law can be used to calculate the magnetic field in situations with a high degree of symmetry.

Copyright © 2005 Pearson Education, Inc. Copyright © 2005 Pearson Education, Inc.

IMPORTANT NOTE: n is equal to the number of coils per unit length (aka. Coil Density). It is NOT the number of wires!

$$\oint \vec{B} \cdot d\vec{l} = \mu_0 I_{enc}$$

$$B(2\pi r) = \mu_0 I_{enc}$$

$$B(2\pi r) = \mu_0 NI$$

$$B = \frac{\mu_0 N I}{2\pi r}$$

If Δr is small
then $n = \frac{N}{2\pi r}$

$B = \mu_0 n I$

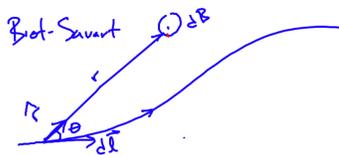
of inner field lines \approx # of outer field lines

$$B = \mu_0 n I$$

28.6 Biot-Savart Law

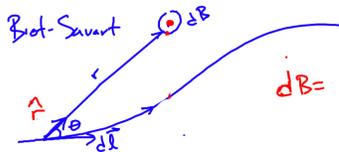
Biot-Savart Law

- B due to current I in straight wire
- Current loop
- Magnetic Dipole Moment
- B due to a wire segment



To find the \vec{B} at any point in space it is necessary to include all currents (not just I_{enc} as in Ampère's Law)
 Magnitude of B

$$B = \frac{\mu_0 I}{4\pi} \int \frac{dl \sin\theta}{r^2} ; B = \int dB$$



$$dB = \frac{\mu_0 I}{4\pi} \frac{dl \times \hat{r}}{r^2}$$

 To find the \vec{B} at any point in space it is necessary to include all currents (not just I_{enc} as in Ampère's Law)
 Magnitude of B

$$B = \frac{\mu_0 I}{4\pi} \int \frac{dl \sin\theta}{r^2} ; B = \int dB$$

\vec{B} due to current I in a straight wire

Magnitude of B

$$B = \frac{\mu_0 I}{4\pi} \int_{-\infty}^{\infty} \frac{dl \sin \theta}{r^2}$$

$$= \frac{\mu_0 I}{4\pi} \int_{-\infty}^{\infty} \frac{dy \sin \theta}{r^2}$$

where $dy = dl$
 $r^2 = y^2 + R^2$
 $\sin \theta = \frac{R}{r} = \frac{R}{\sqrt{y^2 + R^2}}$

\vec{B} due to current I in a straight wire (Page 2)

Magnitude of B

$$B = \frac{\mu_0 I}{4\pi} \int_{-\infty}^{\infty} \frac{R}{r^2} dy$$

$$= \frac{\mu_0 I}{4\pi} \int_{-\infty}^{\infty} \frac{R}{r^3} dy$$

$$B = \frac{\mu_0 I}{4\pi} \int_{-\infty}^{\infty} \frac{R}{(y^2 + R^2)^{3/2}} dy = \frac{\mu_0 I R}{4\pi} \left[\frac{y}{R^2 \sqrt{y^2 + R^2}} \right]_{-\infty}^{\infty}$$

$$= \frac{\mu_0 I R}{4\pi} \frac{2}{R^2} = \frac{\mu_0 I}{2\pi R}$$

$$dB = \frac{\mu_0}{4\pi} \frac{I dl \times \hat{r}}{r^3}$$

$l \sin \theta$

$\mu \times E$
 $\mu \times B$

Biot-Savart
 \vec{B} due to a current loop

$$dB = \frac{\mu_0 I}{4\pi} \frac{dl \times \hat{r}}{r^2}$$

$$\int_0^{2\pi} \sin \phi \rightarrow 0$$

$$dB \cos \phi = dB \frac{R}{h}$$

$$dB \frac{\mu_0 I R}{4\pi h^2} dl = \frac{\mu_0 I}{4\pi}$$

Biot-Savart \vec{B} due to current loop

$$h = \sqrt{R^2 + x^2}$$

$$d\vec{l} \times \hat{r} = dl \sin 90^\circ = dl$$

Due to symmetry $\int dB_{\perp} \rightarrow 0$

$$dB_{||} = dB \cos \phi = dB \frac{R}{h} = \frac{\mu_0 I}{4\pi h^2} dl \times \hat{r} \left(\frac{R}{h} \right)$$

$$B_{||} = \frac{\mu_0 I R}{4\pi h^3} \int_0^{2\pi} dl = \frac{\mu_0 I R^2}{2 h^3} = \frac{\mu_0 I R^2}{2 (R^2 + x^2)^{3/2}}$$

① $x=0$

$$\frac{\mu_0 I R^2}{2 (R^2 + x^2)^{3/2}} \Big|_{x=0} = \frac{\mu_0 I}{2R} = B_{\max}$$

$M = NIA$
 Not permeable
 $M = \mu_0$ Magnetic dipole moment
 $N = \#$ of loops
 $I =$ Current
 $A =$ Area of loop
 $B = \frac{\mu_0 I R^2}{2(R^2+x^2)^{3/2}} = \frac{\mu_0 I \pi R^2}{2\pi(R^2+x^2)^{3/2}} \rightarrow \frac{\mu_0 NIA}{2\pi(R^2+x^2)^{3/2}}$
 $B = \frac{\mu_0 \mu}{2\pi(R^2+x^2)^{3/2}}$ Magnetic dipole

$B = \frac{\mu_0 \mu}{2\pi(R^2+x^2)^{3/2}}$
 $\textcircled{C} x \gg R \quad B = \frac{\mu_0 \mu}{2\pi(x^2)^{3/2}} = \frac{\mu_0 \mu}{2\pi x^3}$ (dipole on x-axis)
 Similar to $E = \frac{1}{4\pi\epsilon_0} \frac{p}{x^3}$
 $\textcircled{C} x = 0 \quad B = \frac{\mu_0 \mu}{2\pi R^3}$

$dB = \frac{\mu_0 I}{4\pi r^2} dl \sin\theta$
 $dB = \frac{\mu_0 I}{4\pi r^2} dl$
 $B = \frac{\mu_0 I}{4\pi R^2} \int_0^{\pi/2} dl = \frac{\mu_0 I}{4\pi R^2} \left[\frac{\pi R}{2} - 0 \right]$
 $B = \frac{\mu_0 I}{8R}$

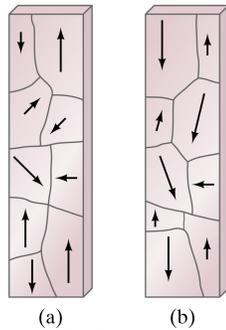
28.7 Magnetic Materials - Ferromagnetism

Ferromagnetic materials are those that can become strongly magnetized, such as iron and nickel.

These materials are made up of tiny regions called domains; the magnetic field in each domain is in a single direction.

28.7 Magnetic Materials - Ferromagnetism

When the material is unmagnetized, the domains are randomly oriented. They can be partially or fully aligned by placing the material in an external magnetic field.



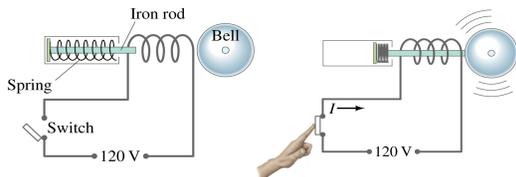
28.7 Magnetic Materials - Ferromagnetism

A magnet, if undisturbed, will tend to retain its magnetism. It can be demagnetized by shock or heat.

The relationship between the external magnetic field and the internal field in a ferromagnet is not simple, as the magnetization can vary.

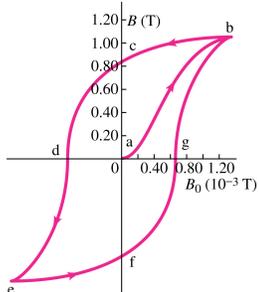
28.8 Solenoids and Electromagnets

If a piece of iron is inserted in the solenoid, the magnetic field greatly increases. Such electromagnets have many practical applications.



28.9 Magnetic Fields in Magnetic Materials; Hysteresis

Starting with unmagnetized material and no magnetic field, the magnetic field can be increased, decreased, reversed, and the cycle repeated. The resulting plot of the total magnetic field within the ferromagnet is called a hysteresis curve.



Copyright © 2005 Pearson Prentice Hall, Inc.

Summary of Chapter 28

- Magnitude of the field of a long, straight current-carrying wire:

$$B = \frac{\mu_0 I}{2\pi r}$$

- Parallel currents attract; antiparallel currents repel

Summary of Chapter 28

- **Magnetic field inside a solenoid:**

$$B = \mu_0 IN/l$$

- **Ampère' s law:**

$$\Sigma B_{\parallel} \Delta l = \mu_0 I_{\text{encl}}$$
